

Classical Information-Theoretical View of Physical Measurements and Generalized Uncertainty Relations

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General characterizations of physical measurements are discussed within the framework of the classical information theory. The uncertainty relation for simultaneous measurements of two physical observables is defined in this framework for generalized dynamic systems governed by a Sturm–Liouville type of equation of motion. In the first step, the reduction of Kennard–Robertson type uncertainties due to boundary conditions with a mean-square error is discussed quantitatively with reference to the information entropy. Several concrete examples of generalized uncertainty relations are given. Then, by considering disturbance effects, a universally valid uncertainty relation is investigated for the generalized equation of motion with a certain boundary condition. Necessary conditions for violation (reduction) of the Heisenberg-type uncertainty relation are discussed in detail. The reduction of the generalized uncertainty relation due to the boundary condition is then tested experimentally by re-analyzing data for measured electron densities in a hydrogen molecule encapsulated in a fullerene C₆₀ cage.

INTRODUCTION

The problem of observation in quantum theory is a long-standing one, raised immediately after quantum mechanics was first established. One of the most important topics is interpretation of the uncertainty relation, which was first expounded by Heisenberg[1]. He introduced his uncertainty relation as a principle of quantum mechanics through a Gedanken experiment regarding position and momentum measurements of a point particle using an imaginary gamma-ray microscope. Kennard[2] and Robertson[3] generalized Heisenberg’s uncertainty relation and proved it mathematically as a relation between standard deviations (square roots of variances) associated with a pair of non-commuting operators. Following the publication of their proof, there remained some confusion about the variance of distributions, mean-square measurement errors, and disturbances because of measurements. Recently, uncertainty relations have been clearly understood[4, 5], and a universally valid uncertainty relation has been obtained[6–8]. However, it is still necessary to pursue a better understanding of uncertainty relations and their applications because the observation problem is a key issue of quantum mechanics that has not yet been completely solved. Experiments claiming to demonstrate a violation of the Heisenberg-type uncertainty relation[9] must be carefully considered from various points of view[10].

In this study, we would like to propose a universal view of physical measurements based on the classical information theory. Here “classical” means that aspects such as commutation relations, Hilbert spaces, and operators on those spaces are not introduced *a priori*, as in contrast to the usual discourse of the quantum measurement theory[11, 12]. Hence, all concepts related to physical measurements are defined in terms of classical information theory. Probabilistic aspects of measurements are

introduced through random variables in the framework of the probability theory. Solutions of a classical equation of motion, such as the equation for charged spinor fields, represent a classical charge distribution. The reason why we restrict to the classical theory is that some counterpart of the “quantum effect”, i.e., uncertainty relations, already arises in the classical field theory without any explicit quantization. One aim of this investigation is to clarify the boundary between classical and quantum mechanics in order to achieve a better understanding of the latter.

PHYSICAL MEASUREMENT

We define terms associated with a physical measurement according to the classical information theory[13] as follows. Let \mathcal{X} be a random variable for a given physical system described by the N -tuple, $\boldsymbol{\theta} = \{\theta_1, \dots, \theta_N\}$, where θ_i is the i th physical parameter. The set of all possible values of $\theta_i \in \mathbb{R}$, denoted by Θ , is called the *parameter set*. The random variable \mathcal{X} is distributed according to the probability density function $f(x; \boldsymbol{\theta}) \geq 0$, which is normalized as $\int_{x \in \Omega} dx f(x; \boldsymbol{\theta}) = 1$, where $x \in \mathbb{R}$ is one possible value of the whole event ($= \Omega$). For physical applications, we introduce the *probability amplitude* defined by

$$|\psi(x; \boldsymbol{\theta})|^2 = f(x; \boldsymbol{\theta}).$$

It is assumed that the behavior of the physical system is determined by the probability amplitude rather than the probability density. This is by analogy with the quantum mechanical amplitude. However, the introduction of an amplitude does not immediately mean that the theory has been quantized. Considering the probability density, the probability amplitude is only by multiplication with a unitary operator, which implies that the amplitude contains more information than the density.

A piece of *experimental apparatus* is assumed to output numbers distributed according to the probability density. Any resulting set of numbers, $\mathcal{X}_n = \{x_1, \dots, x_n\}$, drawn independently and identically distributed (*i.i.d.*), is called the *experimental data*. The estimate the physical parameter is called a *measurement*. Because the experimental data is *i.i.d.*, the corresponding probability density function can be expressed as a product:

$$f(\mathcal{X}_n; \boldsymbol{\theta}) = \prod_{j=1}^n f(x_j; \boldsymbol{\theta}).$$

A function mapping the experimental data to one possible value of the parameter set such as

$$T_i : \mathcal{X}_n \rightarrow \Theta : \{x_1, \dots, x_n\} \mapsto \tilde{\theta}_i$$

is called an *estimator* for the i th physical parameter, denoted by $T_i(\mathcal{X}_n) = \tilde{\theta}_i$. The *experimental error* in the i th physical parameter is defined as the root mean square error:

$$\epsilon_i = E[(T_i(\mathcal{X}_n) - \theta_i)^2]^{1/2},$$

where θ_i is the true value of the i th physical parameter. The true values of physical parameters are unknown, but a mean-square error can be reduced below any desired value by accumulating a sufficiently large amount of experimental data, thanks to the law of large numbers. If the mean value of the experimental error is zero, $E_{\theta_i}[\tilde{\theta}_i - \theta_i] = 0$, after accumulating an infinite number of statistics, that estimator is called an *unbiased estimator*. Among such estimators, the one giving the least error is called the *best estimator*.

Simultaneous measurements of two physical parameters are described as follows. For the random variable, \mathcal{X} , with two physical parameters $\boldsymbol{\theta} = \{\theta_1, \theta_2\}^T$, the experimental data with n samplings can be expressed as $\mathcal{X}_n = \{\mathbf{x}_1, \dots, \mathbf{x}_n\} = \{(x_1^1, x_2^1)^T, \dots, (x_1^n, x_2^n)^T\}$. The probability density of the experimental data is expected to be a Gaussian distribution with two variables:

$$f(\mathbf{x}_j; \boldsymbol{\theta}) = \frac{1}{2\pi|\boldsymbol{\sigma}|^{1/2}} \exp(-(\mathbf{x}_j - \boldsymbol{\theta})^T \boldsymbol{\sigma}^{-1} (\mathbf{x}_j - \boldsymbol{\theta})/2),$$

thanks to the central limit theorem. Here, $\boldsymbol{\sigma}$ is the covariance matrix of the data. When two parameters can be measured independently, the probability density function of the data becomes

$$f(\mathbf{x}_j; \boldsymbol{\theta}) = \prod_{i=1,2} \frac{1}{\sqrt{2\pi}\sigma_i^2} \exp\left(-\frac{(x_j^i - \theta_i)^2}{2\sigma_i^2}\right).$$

In this case, it is known that the best estimators for physical parameters and experimental errors are given as follows:

$$\begin{aligned} T_i(\mathcal{X}_n) &= \frac{1}{n} \sum_{j=1}^n x_j^i = \tilde{\theta}_i, \\ \epsilon_i(\mathcal{X}_n)^2 &= \frac{1}{n} \sum_{j=1}^n (x_j^i - \tilde{\theta}_i)^2 = \tilde{\sigma}_i^2, \end{aligned} \quad (1)$$

for $i=1,2$.

We now introduce quantitative informational properties. The N -tuple of random variables,

$$V_i = \frac{\partial \log f(\mathbf{x}, \boldsymbol{\theta})}{\partial \theta_i},$$

is called the *score*. It can be shown that the expectation value of the score is zero[13]. The score represents the sensitivity of the experimental data to the i th physical parameter. A large value of the score means that the experimental data is sensitive to the i th parameter and is expected to give a small error. The score for the experimental data can be shown to be, $V_i(\mathcal{X}_n) = \sum_{j=1}^n V_i(x_j)$, because the data is *i.i.d.* The covariance matrix of the score

$$J_{ij}(\boldsymbol{\theta}) = \int d\mathbf{x} f(\mathbf{x}; \boldsymbol{\theta}) \frac{\partial \log f(\mathbf{x}; \boldsymbol{\theta})}{\partial \theta_i} \frac{\partial \log f(\mathbf{x}; \boldsymbol{\theta})}{\partial \theta_j} \quad (2)$$

is called the *Fisher information matrix* (FIM). FIM of the experimental data can be shown to be $J_{ij}(\mathcal{X}_n; \boldsymbol{\theta}) = nJ_{ij}(\boldsymbol{\theta})$, once again, because the data is *i.i.d.* $\mathbf{T} = \{T_1, \dots, T_N\}$ is an unbiased estimator, and $\boldsymbol{\Sigma}(\boldsymbol{\theta})$ is the covariance matrix of the data. Then, the Cram r–Rao inequality

$$\boldsymbol{\Sigma}(\boldsymbol{\theta}) \geq \mathbf{J}^{-1}(\boldsymbol{\theta}) \quad (3)$$

holds[14, 15] true as a matrix inequality, i.e., each element on the left-hand side is greater than or equal to each corresponding element on the right-hand side. This is one of the key things to consider when discussing uncertainty relations[16].

EQUATION OF MOTION

The equation of motion (EoM) is a differential equation describing the time evolution of the physical system. We assume that the physical system is governed by the probability amplitude, which is a solution of EoM. Here, we assume that EoM satisfies the following conditions: 1) It is a separable equation with respect to the time variable: 2) The spatial part after time-variable separation will be a holomorphic Sturm–Liouville function[17]: and 3) The Sturm–Liouville differential operator (SL operator) is self-adjoint. The SL-operator is defined by

$$L[\psi(x)] = \frac{d}{dx} \left(p(x) \frac{d}{dx} \psi(x) \right) - q(x) \psi(x) + \lambda r(x) \psi(x),$$

where $p(x)$, $q(x)$, and $r(x)$ are smooth functions given by the dynamical system under consideration. Solving EoM leads to an eigenvalue problem of the form $L[\psi(x)] = 0$ with the following boundary conditions on a finite interval $[a, b]$:

$$\begin{aligned} \psi(a) + \kappa_1 \frac{d\psi(x)}{dx} \Big|_{x=a} &= 0, \\ \psi(b) + \kappa_2 \frac{d\psi(x)}{dx} \Big|_{x=b} &= 0. \end{aligned}$$

Self-adjointness of the SL operator ensures that its eigenfunctions form a complete orthogonal system. By using the complete orthogonal system obtained from EoM, the generalized Fourier transformation (GFT) can be defined by

$$\hat{f}(\lambda) = \int d\xi f(\xi)\psi(\xi; \lambda), \quad (4)$$

where $\psi(\lambda; \xi)$ is the eigen-function of EoM with eigenvalue λ . The existence of GFT with an appropriate integration measure and their inverse transformations are ensured by the generalized expansion theorem[18–21]. For GFT, the conservation of normalization of the two functions is ensured by the Parseval theorem[22, 23]. This set of observables $\{\xi, \lambda\}$ is called the GFT dual pair. In the next section, we will obtain a non-trivial restriction on the uncertainty of a simultaneous measurement of the GFT dual pair.

GENERALIZED UNCERTAINTY RELATIONS WITHOUT DISTURBANCES

Equation of wave motion

The equation of wave motion consists a typical example of EoM discussed in the last section. After separating out the time component, the steady-state solution in an infinitely large box is a plane wave solution of the form

$$K(\xi_1; \xi_2) = \alpha_1 \exp\left(\frac{i}{\hbar}\xi_1\xi_2\right) + \alpha_2 \exp\left(-\frac{i}{\hbar}\xi_1\xi_2\right), \quad (5)$$

where ξ_i are two physical variables (observables) with appropriate dimensions and \hbar is a dimensional physical constant canceling out the dimensions of $\xi_1\xi_2$. It is well known that Eq. (5) specifies a complete orthogonal system, and the integral transformation with a kernel as given by Eq. (5) is the usual Fourier (inverse Fourier) transformation. Suppose that the experimental apparatus has been prepared such that the initial probability density for physical observables ($\xi_{1,2}$) is the Gaussian distribution

$$f(\xi_i, \{\mu_i, \sigma_i\}) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{(\xi_i - \mu_i)^2}{2\sigma_i^2}\right), \quad (6)$$

as would naturally be expected from the central limit theorem. Then, we assume that these two observables constitute the GFT dual pair. In the wave function case, GFT is equivalent to a usual Fourier transformation. Probability amplitudes describing the above probability densities are introduced as follows:

$$\begin{aligned} \psi_1(\xi_1; \{\boldsymbol{\mu}, \boldsymbol{\sigma}\}) &= \sqrt{\frac{1}{\sqrt{2\pi}\sigma_1}} \\ &\times \exp\left(-\frac{(\xi_1 - \mu_1)^2}{4\sigma_1^2} + i\frac{\mu_2(\xi_1 - \mu_1)}{\hbar}\right). \end{aligned}$$

The Gaussian distribution of Eq. (6) is obtained by squaring it. After performing GFT, the probability amplitude of the GFT dual pair, ξ_2 , becomes

$$\begin{aligned} \psi_2(\xi_2; \{\boldsymbol{\mu}, \boldsymbol{\sigma}\}) &= \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} d\xi_1 \psi_1(\xi_1; \{\boldsymbol{\mu}, \boldsymbol{\sigma}\}) \exp\left(-\frac{i}{\hbar}\xi_1\xi_2\right) \\ &= \sqrt{\sqrt{\frac{2}{\pi}} \frac{\sigma_1}{\hbar}} \exp\left(-\frac{(\xi_2 - \mu_2)^2\sigma_1^2}{\hbar^2} - i\frac{\xi_2\mu_1}{\hbar}\right) \end{aligned} \quad (7)$$

Because the transformation kernel in Eq. (5) is a general solution of EoM as a function of the variable ξ_1 , the GFT dual pair amplitude, ψ_2 , is the solution in the GFT dual space, by direct analogy with the relation between configuration and momentum spaces. By squaring the probability amplitude of Eq. (7), one obtains the Gaussian distribution in the form

$$f(\xi_2; \{\mu_2, \sigma_2 = \frac{\hbar}{2\sigma_1}\}) = \sqrt{\frac{2}{\pi}} \frac{\sigma_1}{\hbar} \exp\left(-\frac{2(\xi_2 - \mu_2)^2\sigma_1^2}{\hbar^2}\right),$$

which has a standard deviation of $\sigma_2 = \hbar/2\sigma_1$. Then, standard deviations of the two GFT dual parameters satisfy the relation

$$\sigma_1\sigma_2 = \frac{\hbar}{2}. \quad (8)$$

Next we show that this relation gives a lower bound on measurement errors. Preparation of the physical system with observable ξ_1 and measurement of the observable ξ_2 for the same system can be performed independently. This is justified because we are treating a classical field that has the wave equation as EoM. Then, that total probability density can be expressed as $f(\boldsymbol{\xi}; \{\boldsymbol{\mu}, \boldsymbol{\sigma}\}) = f(\xi_1; \{\mu_1, \sigma_1\})f(\xi_2; \{\mu_2, \sigma_2\})$. FIM can then be obtained from the above formula as follows:

$$\begin{aligned} \mathbf{J}(\mathcal{X}_n; \boldsymbol{\mu}) &= \int_{-\infty}^{\infty} d\xi_1 \int_{-\infty}^{\infty} d\xi_2 f(\boldsymbol{\xi}; \boldsymbol{\mu}) \frac{\partial \log f(\boldsymbol{\xi}; \boldsymbol{\mu})}{\partial \mu_i} \frac{\partial \log f(\boldsymbol{\xi}; \boldsymbol{\mu})}{\partial \mu_j}, \\ &= \begin{pmatrix} \frac{n}{\sigma_1^2} & 0 \\ 0 & \frac{n}{\sigma_2^2} \end{pmatrix} = n\mathbf{J}_1(\boldsymbol{\mu}). \end{aligned} \quad (9)$$

Here we omit the σ -component of FIM, because it is not related to the uncertainty relation. On the other hand, the covariance matrix for simultaneous measurements of the two independent parameters is given as follows:

$$\boldsymbol{\Sigma}(\boldsymbol{\mu}) = \begin{pmatrix} \frac{\sigma_1^2}{n} & 0 \\ 0 & \frac{\sigma_2^2}{n} \end{pmatrix}, \quad (10)$$

according to Eq. (1). By comparing Eqs. (9) and (10), it can be observed that this experiment gives the lower limit of the Cramér–Rao inequality [Eq. (3)]. Then, Eq. (8) gives a lower bound on the initial distributions of the two parameters, and this in turn yields Kennard–Robertson type uncertainty relation, $\sigma_1\sigma_2 \geq \hbar/2$.

Hydrogen atom

As a second example, we consider the following EoM of the SL type operator[24].

$$\frac{d^2}{dr^2}rR(r) + \frac{2}{a_B r}rR(r) - \kappa^2 rR(r) = 0. \quad (11)$$

This is the radial component of the Schrödinger equation in a Coulomb potential when the angular momentum is zero. If we consider a hydrogen atom, $a_B = \hbar^2/m_e e^2 = 0.592 \times 10^{-8} \text{cm}$ is called the *Bohr radius*. It specifies a typical atomic length scale. Because we do not require any quantization, this is the equation for a classical electron field called the *de Broglie field*. Solutions of this equation give the charge density distribution of a classical electron field. A set of solutions normalized to unity in $0 \leq r < \infty$ is given by

$$R_n(r) = \sqrt{\left(\frac{2}{a_B n}\right)^3 \frac{1}{2n^2}} \exp\left(-\frac{r}{a_B n}\right) L_{n-1}^1\left(\frac{2r}{a_B n}\right),$$

where $L_n^\bullet(\bullet)$ are Laguerre polynomials. This set consists a complete orthonormal system satisfying

$$\int_0^\infty dr r^2 R_n(r) R_m(r) = \delta_{nm}. \quad (12)$$

The corresponding eigenvalues can be obtained as $E_n = -\hbar^2 \kappa^2 / 2m_e$ with $\kappa = (a_B n)^{-1}$. Once again we take the initial probability density of the electron to be a Gaussian distribution:

$$\psi(r; \sigma_r) = \left(\frac{1}{2\pi\sigma_r^2}\right)^{\frac{1}{4}} \exp\left(-\frac{r^2}{4\sigma_r^2}\right), \quad (13)$$

$$\begin{aligned} f(r; \sigma_r) &= |\psi(r; \sigma_r)|^2, \\ &= \left(\frac{1}{2\pi\sigma_r^2}\right)^{\frac{1}{2}} \exp\left(-\frac{r^2}{2\sigma_r^2}\right). \end{aligned} \quad (14)$$

One reason why we start with the Gaussian distribution is that it is expected to be obtained from the central limit theorem for the physical measurements of i.i.d. and will lead the minimum uncertainty condition. GFTs of these eigen-functions are given as

$$\phi_n(\sigma_r) = C(\sigma_r) \int_0^\infty dr r^2 \psi(r; \sigma_r) R_n(r), \quad (15)$$

$$\begin{aligned} &= C(\sigma_r) \sum_{m=0}^{n-1} \frac{(-1)^m 2^{\frac{5}{4}+m} (m+2) \Gamma(n)}{\pi^{\frac{1}{4}} m! \Gamma(n-m) (a_0 n)^{\frac{3}{2}+m}} \\ &\times F\left(\frac{m+3}{2}, \frac{1}{2}; \left(\frac{\sigma_r}{a_0 n}\right)^2\right) \sigma_r^{\frac{5}{2}+m}, \end{aligned} \quad (16)$$

where $F(\bullet, \bullet; \bullet)$ is the confluent hypergeometric series, and $C(\sigma_r)$ is an appropriate normalization factor. Because the solutions $R_i(r)$ form a complete orthonormal set of functions, as shown in Eq. (12), the Gaussian

distribution can be expressed as the inverse GFT of an infinite summation:

$$\tilde{\psi}(r; \sigma_r) = \sum_{i=1}^{\infty} \phi_i(\sigma_r) R_i(r).$$

We have checked numerically that this inverse GFT would transfer $\phi_i(\sigma_r)$ back to the original Gaussian distribution, except that it would be close to the origin. Note that atomic units (a.u.)[25] are used in all numerical calculations in this study ($m_e = 1$, $\hbar = 1$, and $e = 1$). In this case, the usual Fourier transformation of $\psi(r; \sigma_r)$ does not have any clear physical meaning because the plane wave solution has no vanishing values at $r = \infty$, whereas $\psi(r \rightarrow \infty; \sigma_r) = 0$ for a hydrogen atom. The GFT dual parameter of the radial coordinate r must be an energy eigenvalue E_n . Probability density functions in the GFT dual space have Gaussian distributions, as shown in FIG. 1. The relation between standard deviations of the initial Gaussian distribution and the corresponding energy spectrum is shown in Fig. 2. We can observe that the uncertainty of the energy spectrum decreases position uncertainty increases. Moreover, products of these two uncertainties are almost constant at $\sigma_r \sigma_E \simeq 1/1.72$. This condition also gives the lower bound from Cramér–Rao inequality because the GFT dual probability density function (ϕ_n) has a Gaussian distribution, and the discussion from the first example can still be applied. A generalized uncertainty relation for this case can be expressed as

$$\sigma_r \cdot \sigma_E \geq \frac{a_B E_a}{1.72}, \quad (17)$$

where E_a is the atomic unit of energy. This relation is similar to the Kennard–Robertson uncertainty, except that the coefficient in front of the dimensional parameters on the right-hand side is $1/1.72$, instead of the usual value of $1/2$.

Let us look at this new relation from another point of view. The reason why a hydrogen atom does not collapse to the size of the proton is usually discussed with only a qualitative reference to the uncertainty relation. Here, we investigate this matter in a quantitative way using the new uncertainty relation. The total energy of the electron can be given as

$$E_H = 3 \frac{p^2}{2} - \frac{1}{r},$$

in a.u. The first and second terms are basically kinetic and potential energies. The factor of 3 in front of the kinetic energy originates from the spatial degree of freedom. Suppose now that the uncertainty relation is $\sigma_p \sigma_r \geq f_u$. In a ground state hydrogen atom, the electron is confined within the Bohr radius, $\sigma_r = a_B = r_0$, which suggests that $\sigma_p = f_u / \sigma_r = f_u / r_0$. The total energy can thus be written as

$$E_H^0 = 3 \frac{f_u^2}{2r_0^2} - \frac{1}{r_0},$$

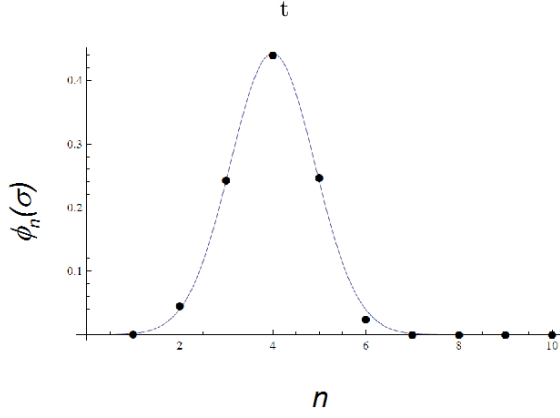


FIG. 1. Example of the probability density function in the GFT dual space for the radial distribution of the classical electron field in a hydrogen atom. The solid line is a Gaussian fit. A Gaussian distribution is assumed for the radial variable, with variance $\sigma_r^2 = 10^2$.

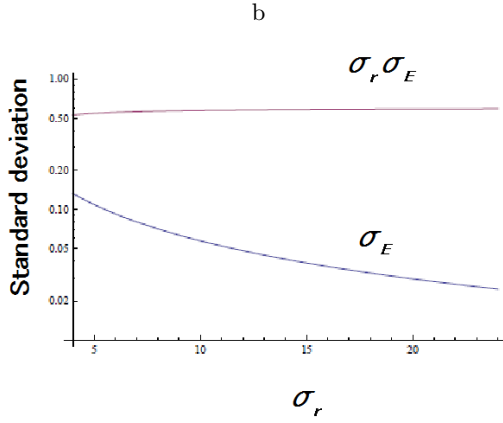


FIG. 2. Relation between standard deviations of the initial Gaussian distribution and the corresponding energy spectrum. The electron mass and Bohr radius are set to unity (a.u.) in calculations.

where r_0 is the hydrogen radius in the ground state. The value r_0 must give the minimum energy, then, it can be obtained as a solution of $\partial E_H^0 / \partial r_0 = 0$, i.e., $r_0 = 3f_u^2$. If we set $r_0 = a_B = 1$, then, we get $f_u = 1/\sqrt{3} = 1/1.732 \dots$ which is close to the factor in the new uncertainty relation. If one can assume, that the uncertainty relation gives the exact hydrogen radius, then the uncertainty relation between GFT dual parameters for the system under the SL operator of Eq. (11) must be

$$\sigma_r \cdot \sigma_E \geq \frac{a_B E_a}{\sqrt{3}}. \quad (18)$$

We can give yet another view of the hydrogen atom in terms of the classical information theory. The entropy of the energy spectrum of the hydrogen atom can be cal-

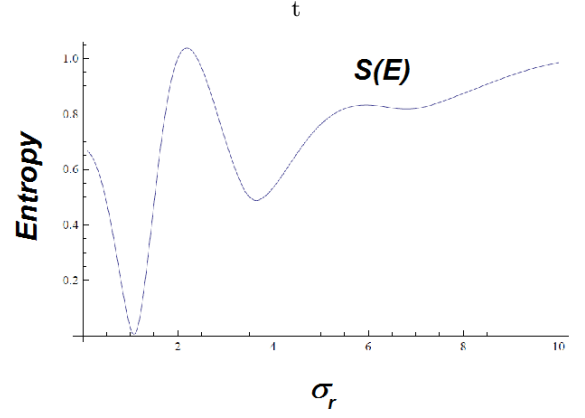


FIG. 3. Entropy obtained from hydrogen energy states and radial distributions as a function of the width of the radial distribution (σ_r). The entropy of hydrogen energy states reaches a minimum at the Bohr radius.

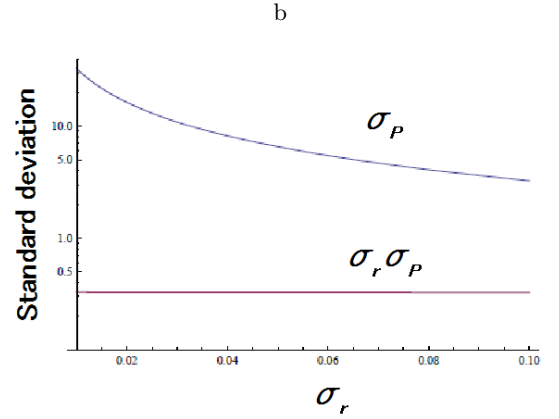


FIG. 4. Width of the radial distribution of the beam multiplied by its momentum as a function of the beam width. GFT can maintain the product of widths of the pair at $\sigma_R \sigma_P = 1/0.30$, where \hbar is set to unity.

culated numerically from Eq. (16) as

$$S(E) = - \sum_{n=1}^{\infty} \phi_n(\sigma_r) \log \phi_n(\sigma_r).$$

Numerical results are shown in FIG. 3 as a function of the width of the radial distribution. The global minimum point of the entropy coincides with the Bohr radius, as shown Fig. (3).

Classical matter field in a cylinder

We now consider a particle beam entering a cylindrical beam pipe. The Schrödinger equation in cylindrical coordinates is considered as EoM for the classical matter field. EoM for a radial variable $R(r)$ with zero angular

momentum can be expressed as

$$\frac{d}{dr} \left(r \frac{dR(r)}{dr} \right) - \frac{n^2}{r} R(r) + (k^2 - \lambda^2) r R(r) = 0,$$

which is also an SL type equation. Solutions with the infinite potential barrier at $r = r_0$ are obtained as

$$R_l^n(r) = \frac{\sqrt{2}}{r_0 |J_{l+1}(z_l^n)|} J_l \left(z_l^n \frac{r}{r_0} \right), \quad (19)$$

where $J_l(x)$ is the l th order Bessel function of the first kind and z_l^n is its n -th zero point. This series of functions constitutes an orthonormal system with normalization given as

$$\int_0^\infty dr \, r R_l^n(r) R_l^m(r) = \delta_{nm}.$$

The corresponding eigenvalues are

$$\begin{aligned} k^2 &= \left(\frac{z_l^n}{r_0} \right)^2 + \lambda^2, \\ P_l^n &= \hbar k, \\ &= \hbar \frac{z_l^n}{r_0}. \end{aligned} \quad (20)$$

Here, λ is the eigenvalue from the appropriate boundary condition in the z -coordinate and will be neglected in the following discussion. Even though a physical constant, \hbar , arises in the eigenvalues, this is a classical theory, and the solution $R_l^n(r)$ represents a classical *de Broglie field*. Suppose a particle beam with Gaussian distribution in the radial direction of the cylindrical coordinate enter a cylinder of radius r_0 . The beam is assumed to be coaxial with respect to the cylinder, so the angular momentum of the beam is zero ($l = 0$). This radial distribution can be expanded in terms of the solutions of Eq. (19) as

$$\phi_n(\sigma_R) = \int_0^{r_0} dr \, r \, \psi(r; \sigma_R) R_0^n(r),$$

where $\psi(r; \sigma_R)$ is the radial distribution of the incident beam represented by Eq. (13). When $\sigma_R \ll r_0$, the above integration can be performed analytically to give

$$\phi_n(\sigma_R) \approx \frac{4\sigma_R^{3/2}}{(2\pi)^{1/4} r_0 J_1(z_0^n)} \exp \left(\frac{\sigma_R z_0^n}{r_0} \right)^2.$$

The usual Fourier dual pair has no clear physical meaning because the solution of EoM with a cylindrical boundary condition is not a plane wave. The GFT dual pair can be given as $\{r, P_0^n = z_0^n/r_0\}$, and GFT transforms the Gaussian to another Gaussian. The width of the P_0^n distribution is proportional to the reciprocal of σ_R , as shown in FIG. 4. The relation between the widths of the GFT pair is found numerically to be $\sigma_R \sigma_P = \hbar/3.0$, which gives a smaller uncertainty than the Kennard–Robertson relation expected from the usual Fourier dual pair. This

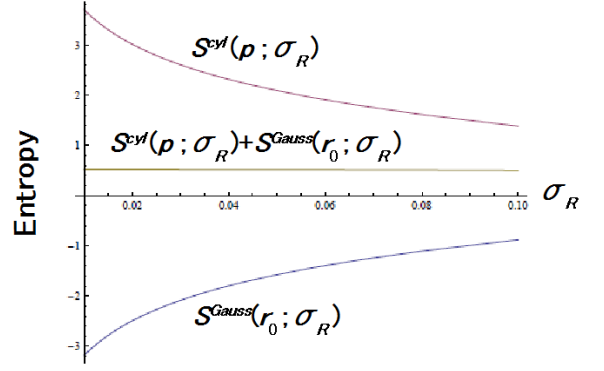


FIG. 5. Entropies of the radial distribution of the beam and those of the GFT dual pair of the momentum eigenstate distribution. \hbar and r_0 are set to unity.

reduction of the uncertainty can be explained with respect to the entropy. The entropy of the radial distribution, which is contained within the cylinder, can be calculated from the probability density function [Eq.(14)] as

$$S^{Gauss}(r < r_0; \sigma_R) = - \int_{-r_0}^{r_0} dr \, f(r; \sigma_R) \log f(r; \sigma_R),$$

whereas the entropy of the momentum distribution can be obtained as

$$S^{cyl}(p; \sigma_R) = - \sum_{n=1}^{\infty} \phi_n(\sigma_R) \log \phi_n(\sigma_R).$$

As the beam width increases, the entropy of the radial distribution increases, whereas that of the momentum distribution decreases such that their sum is maintained to be constant, as shown in FIG. 5. This behavior of entropies is easily understood qualitatively if we recall that the entropy is a measure of the total amount of information in distributions. Under the minimum uncertainty condition, the total amount of information can be maintained constant. Here, let us consider them quantitatively in order to estimate the information gain obtained from the boundary condition. When there are no boundary conditions on radial distributions, the information entropy of the usual Fourier dual pair is

$$S^{Gauss}(\sigma_x) + S^{Gauss}(\sigma_p) = \frac{1}{2} \log(4\pi^2 e^2 \sigma_x^2 \sigma_p^2) + 2\Delta.$$

where Δ is an arbitrary value due to ambiguity in the choice of integration measure. Then, the relation between the entropy and mean-square errors can be expressed as

$$\begin{aligned} \sigma_x \sigma_p &= \frac{1}{2\pi} \exp(S(\sigma_x) + S(\sigma_p) - 1 - 2\Delta), \\ &= \frac{\hbar}{2} \exp(S(\sigma_x) + S(\sigma_p)). \end{aligned}$$

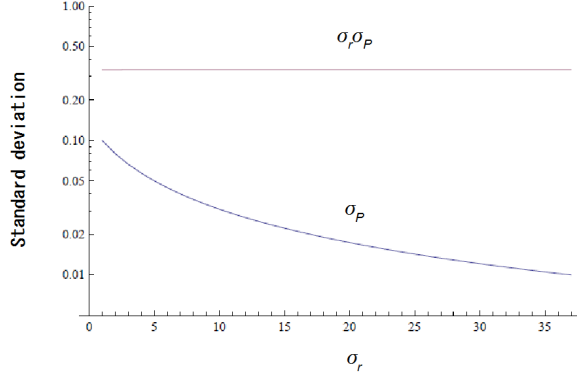


FIG. 6. Width of the radial distribution of the initial field multiplied its GFT dual momentum. GFT can maintain the product of widths of the pair at $\sigma_r \sigma_p = 1/2.9$, where \hbar is set to unity.

Here, we set Δ equal to $-1/2 \log(e\pi\hbar)$ to obtain the minimum uncertainty relation when $S(\sigma_x) + S(\sigma_p) = 0$. The average information due to the cylindrical boundary condition can be estimated as follows. The radial distribution of the incident beam is assumed to be the Gaussian distribution, as given in Eq. (6). The total amount of information in the cylinder of radius r_0 can be calculated as

$$I(r_0, \sigma) = \int_{-r_0}^{r_0} dr f(r, \{0, \sigma_R\}) \\ = \text{erf}\left(\frac{r_0}{\sqrt{2}\sigma_R}\right),$$

where $\text{erf}(\bullet)$ is the error function. The entropy within the cylinder can be calculated as

$$S^{cyl}(r_0; \sigma_R) = -I(r_0, \sigma_R) \log I(r_0, \sigma_R).$$

The maximum value of the total information is found to be $S^{cyl} = e^{-1}$ by solving $\partial S^{cyl}/\partial r_0 = 0$. This amount of information gain due to the cylindrical boundary condition can decrease the minimum uncertainty according to

$$\sigma_x \sigma_p = \frac{\hbar}{2} \exp\left(-\frac{1}{e}\right), \\ \simeq \frac{\hbar}{2.9},$$

which is consistent with the numerical result shown in FIG. 4. This reduction of the uncertainty relation is due to the information gain from the cylindrical boundary condition.

Classical matter field in a sphere

The last example is a classical matter field confined in a sphere. The calculations are almost the same as those in last the section, we only list the results here:

- EOM for the radial coordinate with zero angular momentum:

$$\frac{d}{dr} \left(r \frac{dR(r)}{dr} \right) + k^2 r R(r) = 0$$

- Solutions of EoM:

$$R_n(r) = \sqrt{\frac{2}{r_0}} \frac{\sin(n\pi r/r_0)}{r}$$

- Orthonormality relation:

$$\int_0^{r_0} dr r^2 R_n(r) R_m(r) = \delta_{nm}$$

- Eigenvalue for the radial equation:

$$P_n = \hbar k \\ = \hbar \frac{n\pi}{r_0}, \quad (n = \pm 1, \pm 2, \dots)$$

- GFT and inverse GFT for the Gaussian distribution:

$$\phi_n(\sigma_R) = \int_0^{r_0} dr r^2 \psi(r; \sigma_R) R_n(r) \\ \psi(r; \sigma_R) = \sum_{i=1}^{\infty} \phi_i(\sigma_R) R_i(r)$$

- GFT dual integration with approximation $\sigma_R \ll r_0$:

$$\phi_n(\sigma_R) \simeq \int_0^{\infty} dr r^2 \psi(r; \sigma_R) R_n(r) \\ = \frac{2^{9/4} \pi^{5/4}}{r_0^{3/2}} n \sigma_R^{5/2} \exp\left(-\frac{n\pi\sigma_R}{r_0}\right)^2$$

- Generalized uncertainty relation(see FIG. 6):

$$\sigma_R \sigma_p \simeq \frac{\hbar}{2.9}$$

In this case, mean-square errors once again give the Kennard–Robertson type uncertainty relation with a factor of $\hbar/2.9$ instead of $\hbar/2$, which is consistent with the information gain because of the boundary condition, same as that as in the previous example.

GENERALIZED UNCERTAINTY RELATIONS WITH DISTURBANCES

The universally valid uncertainty relation

Next we consider a disturbance due to the measurements themselves. It is assumed that the initial conditions of the physical system agree with the minimum uncertainty condition, with mean values of $\{\mu_1, \sigma_1^2\}$ and variances of $\{\mu_2, \sigma_2^2\}$. The two observables $\{\mu_1, \mu_2\}$ are assumed to be a GFT-pair. Estimators associated with this measurement are assumed to be unbiased. After simultaneous measurements of physical parameters $\{\mu_1, \mu_2\}$, final distributions are expected to be Gaussian because of the central limit theorem. The disturbance, δ_i^2 , is defined as an increase in variance in the distribution of the i th observable after the measurement. The convolution of two Gaussian distributions with mean values and variances as $\{\mu_1, \sigma_1^2\}$ and $\{\mu_2, \sigma_2^2\}$ yields the Gaussian distribution with $\{\mu_1, \tilde{\sigma}_1^2 = \sigma_1^2 + \delta_1^2\}$ and $\{\mu_2, \tilde{\sigma}_2^2 = \sigma_2^2 + \delta_2^2\}$. Initial and final distributions are not necessarily a GFT pair. To find the minimum uncertainty condition after the measurement, we assume that the measurement has been performed with very weak coupling and gives a minimum uncertainty pair of disturbances with $\delta_1\delta_2 = \hbar/2$. Then, standard deviations after the measurement can be written in the form

$$\begin{aligned} \tilde{\sigma}_1^2 \tilde{\sigma}_2^2 &= \text{Min}[\tilde{\sigma}_1^2 \tilde{\sigma}_2^2], \\ &= (\sigma_1^2 + \delta_1^2) \left(\sigma_2^2 + \frac{\hbar^2}{4\delta_1^2} \right). \end{aligned} \quad (21)$$

The minimum uncertainty condition after the measurement is given by δ_1 as $\partial \tilde{\sigma}_1^2 \tilde{\sigma}_2^2 / \partial \delta_1 = 0$ such that

$$\begin{aligned} \frac{\partial \tilde{\sigma}_1^2 \tilde{\sigma}_2^2}{\partial \delta_1} &= 2\delta_1 \sigma_2^2 - \frac{\hbar^2 \sigma_1^2}{2\delta_1^3} = 0, \\ \Rightarrow \sigma_1 &= \sqrt{\frac{\hbar \sigma_1}{2 \sigma_2}}. \end{aligned} \quad (22)$$

Then, the formula

$$\tilde{\sigma}_1 \tilde{\sigma}_2 \geq \sigma_1 \sigma_2 + \frac{\hbar}{2} \quad (23)$$

follows from (21) and (22). Under this condition, we derive the universally valid uncertainty relation (UVUR)[6–8]:

$$\sigma_1 \delta_2 + \delta_1 \sigma_2 + \delta_1 \delta_2 \geq \frac{\hbar}{2}. \quad (24)$$

From Eq. (23) and the positivity of standard deviations, $\sigma_i, \delta_i \geq 0$, one can obtain

$$\begin{aligned} (\sigma_1 + \delta_1)^2 (\sigma_2 + \delta_2)^2 &\geq (\sigma_1^2 + \delta_1^2)(\sigma_2^2 + \delta_2^2), \\ &= \tilde{\sigma}_1^2 \tilde{\sigma}_2^2, \\ &\geq \left(\sigma_1 \sigma_2 + \frac{\hbar}{2} \right)^2. \end{aligned}$$

Then, the inequality

$$\sigma_1 \sigma_2 + \sigma_1 \delta_2 + \delta_1 \sigma_2 + \delta_1 \delta_2 \geq \sigma_1 \sigma_2 + \frac{\hbar}{2}$$

is obtained. UVUR, Eq. (24), follows immediately from this formula[26].

Example: Hydrogen atom in a C₆₀ cage

We now discuss the possibility of observing a violation of the lower bound in the Heisenberg-type uncertainty relation, $\delta_1 \delta_2 \geq \hbar/2$ (\hbar is written as $\tilde{\hbar}$ in this section.). We have re-investigated position measurements of electrons in a hydrogen molecule trapped in a fullerene C₆₀ cage. In 2005, Komatsu et al. succeeded in encapsulating molecular hydrogen in fullerene C₆₀ (H₂@C₆₀) with an efficiency of approximately 100%[27]. Sawa et al. measured the electron density in the closed C₆₀ cage using X-rays from a synchrotron light source[28]. The electron density was measured using X-rays of wavelength 0.0998 nm. The H₂@C₆₀ sample was maintained at 50K. It has been confirmed experimentally that the rotational mode of H₂@C₆₀ is almost eliminated at this temperature[29]. The inner diameter of fullerene C₆₀ is known to be approximately 0.7 nm. Here, we employ a radius of 0.36 nm, as used in [30]. Electrons belonging to H₂@C₆₀ can be described by the Schrödinger equation with the boundary condition that the electron density is zero for $r \geq 0.36$ nm. The equation for the hydrogen atom has been solved numerically using *Mathematica*[31]. Here, we assume that energy eigenvalues are well approximated by those of the hydrogen atom for smaller principal quantum numbers. The solution proportional to e^{+r} , which is abandoned as a solution for molecular hydrogen in vacuum, is allowed for H₂ in the C₆₀ cage. Energy eigenvalues are listed in TABLE. I, along with the values in vacuum. All solutions have zero angular momentum, because there no solutions with non-zero angular momentum in a spherically symmetric cage of radius 0.36 nm. Before the measurement, the electrons must be in the ground state. The uncertainty in the electron energy originates only from thermal fluctuations in electron energies, which is estimated to be $\sigma_E = 4.31 \times 10^{-3}$ eV at a

n	H2(Vac.)	H ₂ @C ₆₀ (Sol.1)	H ₂ @C ₆₀ (Sol.2)
1	-13.62	-13.62	-13.62
2	-3.41	-1.14	-1.14
3	-1.51	-	1.14
4	-0.85	-	13.62

TABLE I. Energy eigenvalues of a hydrogen atom with boundary condition from the C₆₀ cage. Here, n is the principal quantum number. In the C₆₀ cage, the solutions proportional to e^{+r} (Sol.2) are permitted as are those proportional to e^{-r} (Sol.1), in contrast with the situation in vacuum (Vac.).

temperature of 50 K. The electron position in the ground state has a distribution with variance equal to the square of the Bohr radius. Hence, the Bohr radius is considered as the uncertainty in the initial electron position, i.e., $\sigma_r = a_B = 5.29 \times 10^{-2}$ nm. The electron may be excited to one of the excited states listed in TABLE. I after the measurement. Then, the energy uncertainty of the electron is at the most $\delta_E = 27.24$ eV. The uncertainty in the electron density measurement is not clearly given, but the distribution of the electron density with respect to the radius has been measured very clearly, and the estimated number in the electrons in $H_2@C_{60}$ is given as 1.9 ± 0.4 [30, 32]. If we assume $\delta_r = 1 \times 10^{-2}$ nm, the calculated electron density distribution is consistent with the figure and the estimated number of electrons in the cage is found to be 2.0 ± 0.4 , which is consistent with the experimental result. We thus use the value $\delta_r = 1 \times 10^{-2}$ nm for the position uncertainty of the measurement[33]. In conclusion, we obtain the following uncertainties:

$$\begin{aligned}\delta_E \times \sigma_r &\simeq 1.44 \text{ eV nm}, \\ \sigma_E \times \delta_r &\simeq 4.31 \times 10^{-5} \text{ eV nm}, \\ \delta_E \times \delta_r &\simeq 2.72 \times 10^{-1} \text{ eV nm}, \\ \frac{a_b E_0}{2} &\simeq 3.60 \times 10^{-1} \text{ eV nm}.\end{aligned}$$

Here, we observe that Heisenberg uncertainty pair, $\delta_E \times \delta_r$, exhibits smaller values than the expected vales $a_b E_0/2$.

SUMMARY AND CONCLUSIONS

We have formulated the physical measurement process on the basis of the classical information theory. All processes related to measurements are treated without introducing any quantization of the physical system. In other words, all physical quantities are described by “c-numbers”. The probabilistic behavior of physical measurements comes from the assumption that the experimental data are random variables obeying some probability law. Even in this classical context, essential properties of uncertainty relations are exhibited. The Kennard–Robertson type of uncertainty relation arises for two physical quantities related to one another by Fourier transformation. Although Fourier transformation plays an essential role, it is not the only transformation leading to an uncertainty relation. We have investigated GFT dual pairs of physical quantities governed by the Sturm–Liouville type differential equations and have obtained a generalized uncertainty relation for such GFT dual pairs. In addition, we have shown that Gaussian distributions realize the minimum uncertainty condition using the Cramèr–Rao inequality, and the minimum uncertainty condition can give a smaller error than that implied by the usual

Kennard–Robertson lower limit. This reduction of uncertainties can be understood quantitatively in terms of the information entropy because of boundary conditions. Another important result of this study is that the probability amplitude, which is defined as a square root of the probability density, plays as essential role in introducing the GFT dual pair of physical quantities and obtaining the generalized uncertainty relation.

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